

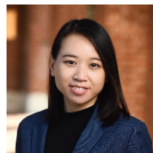


# Efficient Approximate Predictive Inference Under Feedback Covariate Shift with Influence Functions

Drew Prinster, Suchi Saria, Anqi Liu

Johns Hopkins University

2023



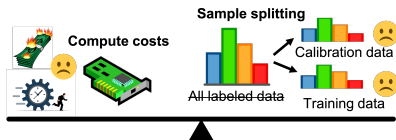
# Presentation Outline

- 1 Introduction
- 2 Related Work: High-Level Overview
- 3 Technical Background and Proposed Method
- 4 Experimental Results
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# Two Key Challenges in Conformal Prediction

## 1. Resource constraints (compute & available data)

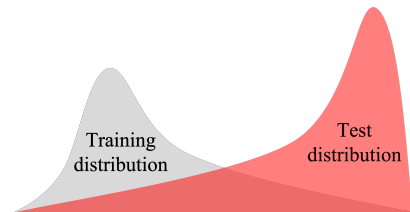
- *Computational budget*: e.g., extensive model retraining
- *Data-availability demands*: e.g., sample-splitting (which can harm model performance, especially in low data regime)



## 2. Data shifts

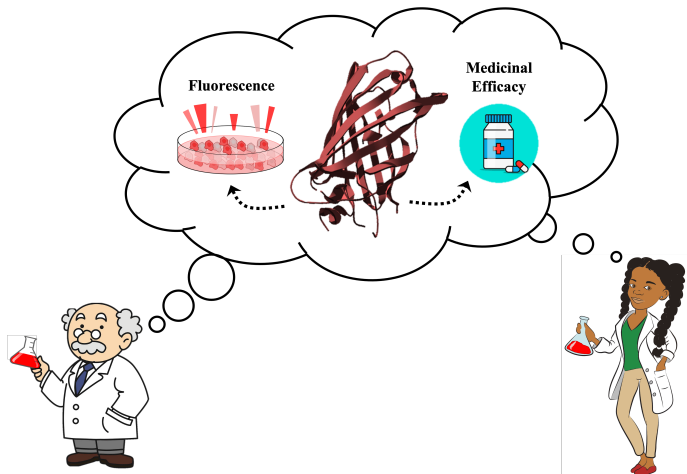
Real world data are often **not exchangeable!**

Common shifts between training & test data distributions can break standard conformal methods.



Our work (today and prior) is at the intersection of these challenges.

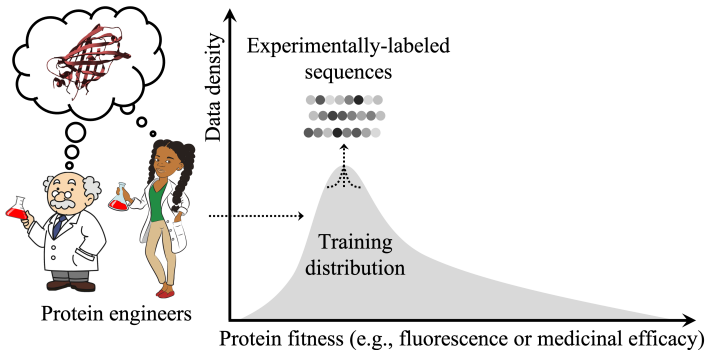
# Biomolecular Design Setting



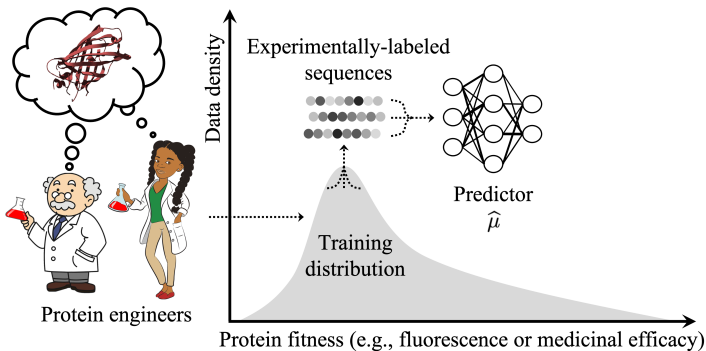
Detailed description in Fannjiang, Bates, Angelopoulos, Listgarten, and Jordan (2022)



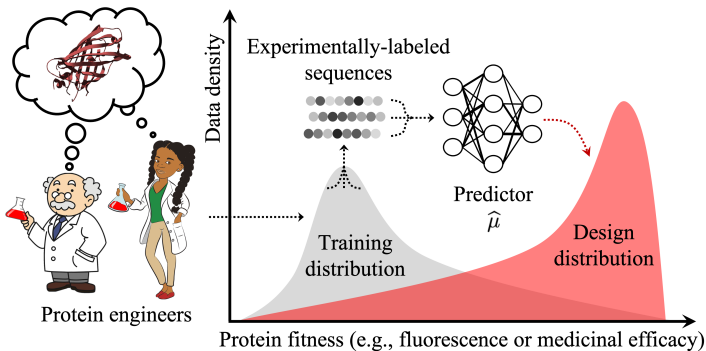
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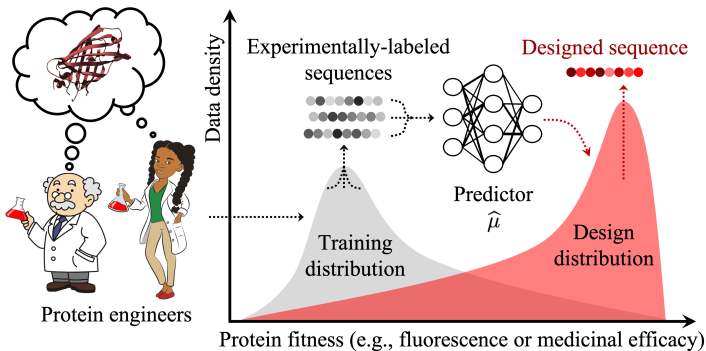
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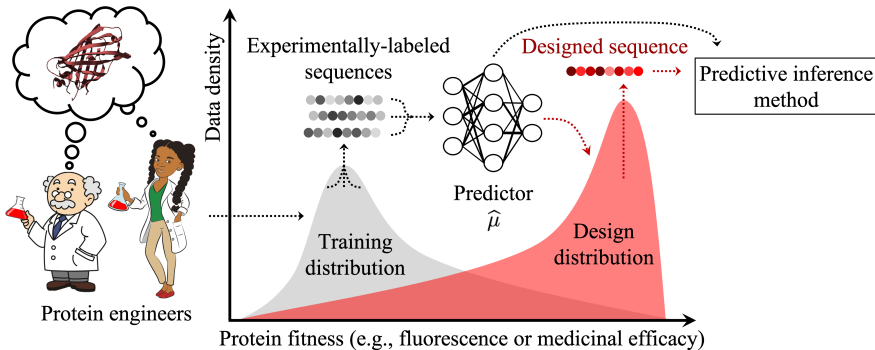
# Biomolecular Design Setting



# Biomolecular Design Setting



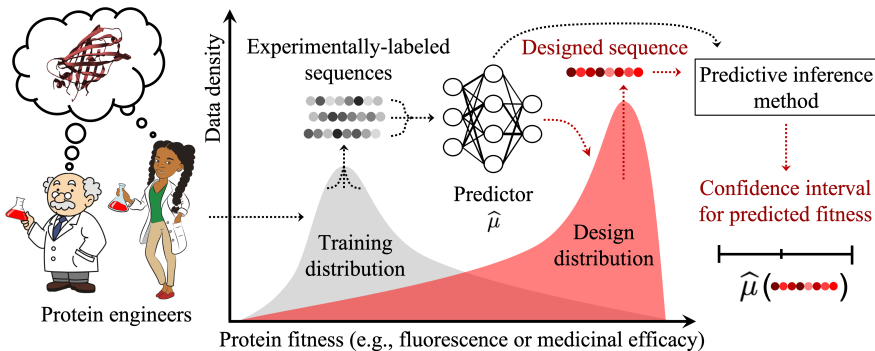
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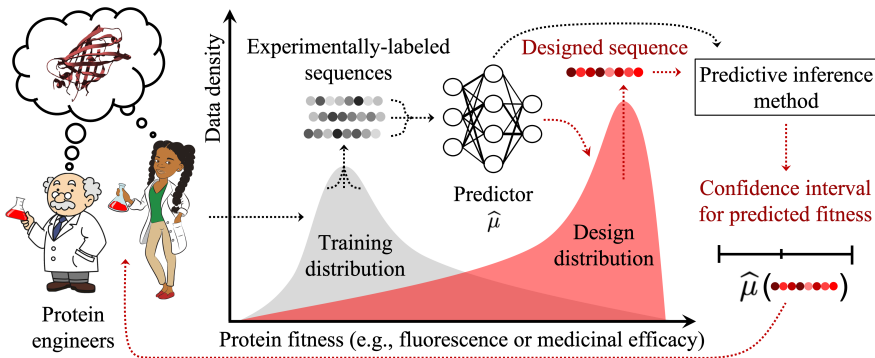
# Biomolecular Design Setting

Introduction

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# Biomolecular Design Setting



# Background: Feedback Covariate Shift (FCS)

## Standard conformal prediction “SCS”:

$$Z_i = (X_i, Y_i) \stackrel{\text{i.i.d.}}{\sim} P_X^{\text{train}} \times P_{Y|X}, \\ i = 1, \dots, n$$

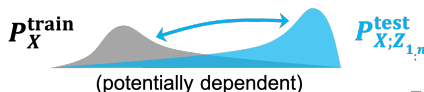
$$(X_{n+1}, Y_{n+1}) \sim P_X^{\text{test}} \times P_{Y|X}$$



**Feedback covariate shift “FCS”** (One-shot biomolecular design is an instance; Fannjiang et al. (2022)):

$$Z_i = (X_i, Y_i) \stackrel{\text{i.i.d.}}{\sim} P_X^{\text{train}} \times P_{Y|X}, \\ i = 1, \dots, n$$

$$(X_{n+1}, Y_{n+1}) \sim P_{X;Z_{1:n}}^{\text{test}} \times P_{Y|X}$$





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# Related Work: Efficiency Tradeoffs

Assumptions on train  
vs. test data:

Exchangeable (e.g., IID)

$$P_X^{\text{training}} = P_X^{\text{test}}$$

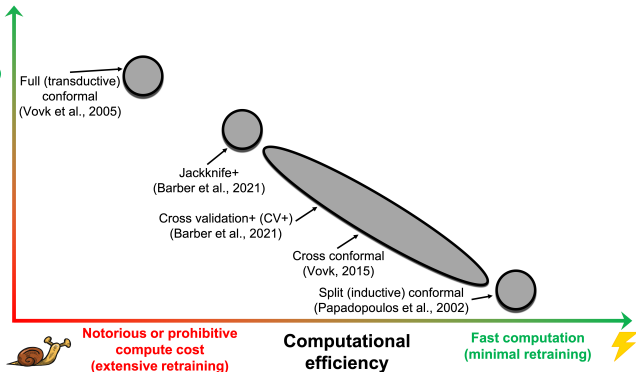
Strong model  
performance due to  
efficient data use  
(no sample splitting)



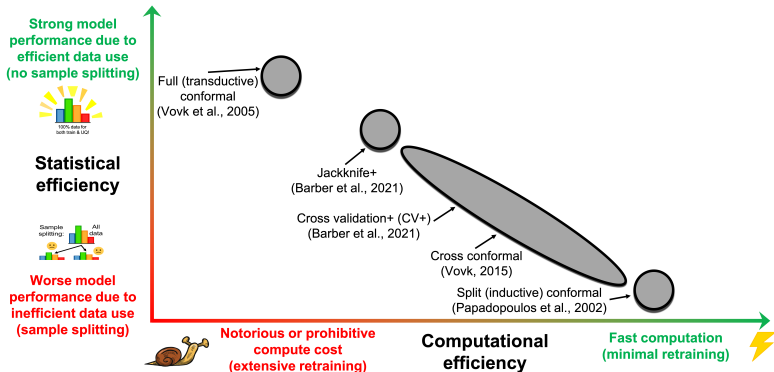
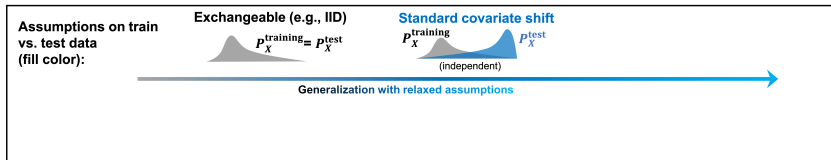
Statistical  
efficiency



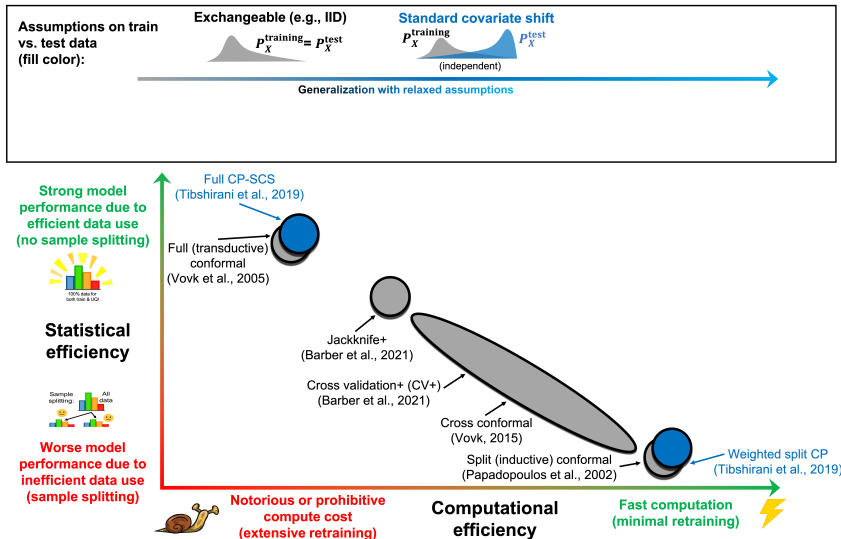
Worse model  
performance due to  
inefficient data use  
(sample splitting)



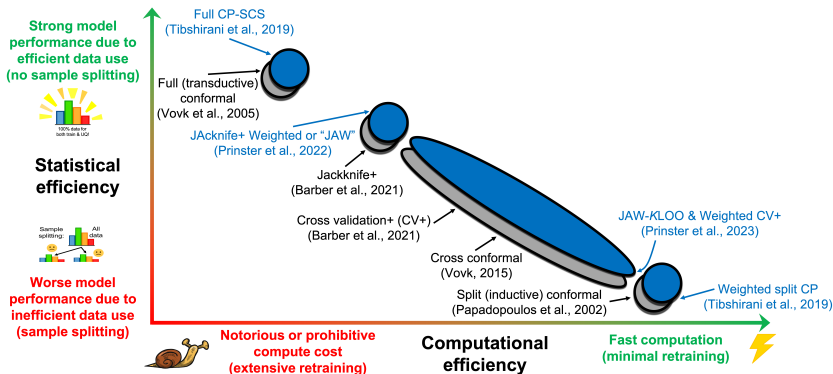
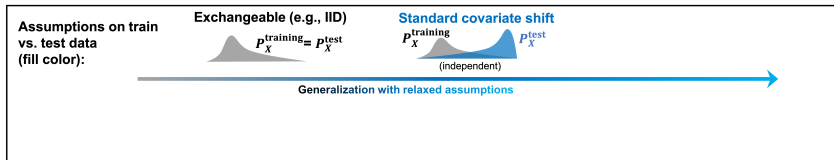
# Related Work: Feedback Covariate Shift (FCS)



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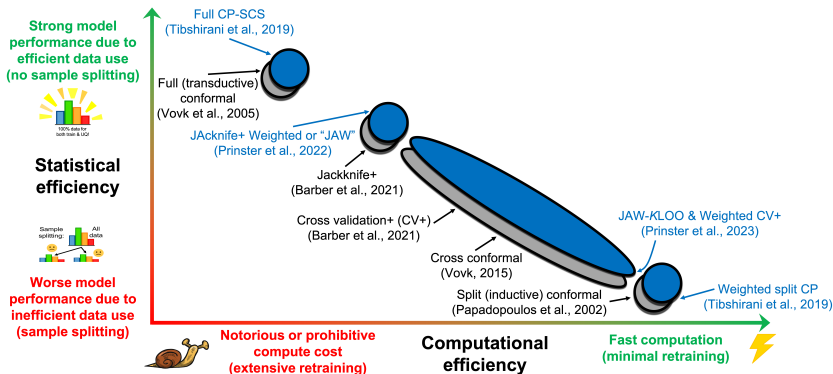
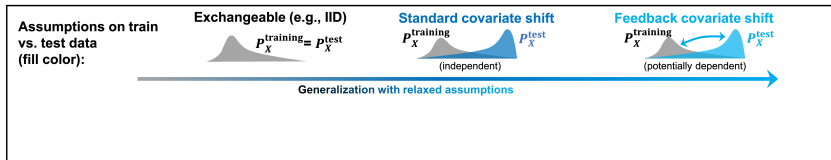
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Related Work: High-Level Overview

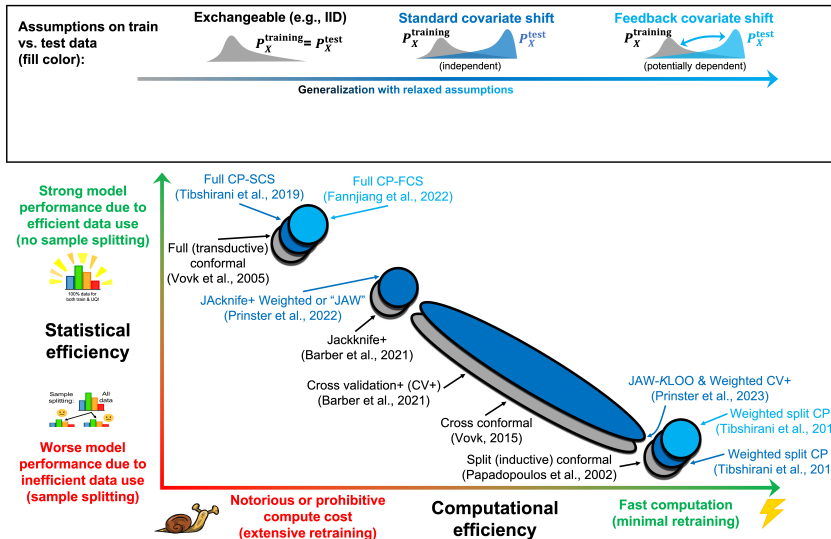
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# Related Work: Feedback Covariate Shift (FCS)

Related Work: High-Level Overview

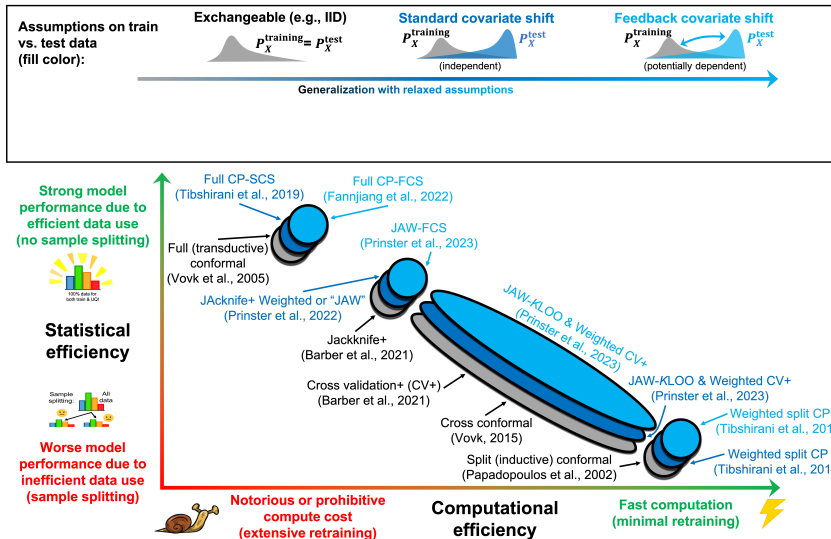
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# Related Work: Feedback Covariate Shift (FCS)

Related Work: High-Level Overview

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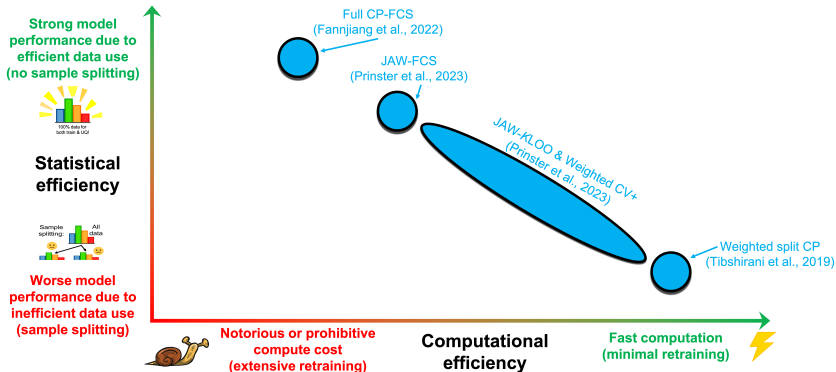




# Related Work: Feedback Covariate Shift (FCS)

Related Work: High-Level Overview

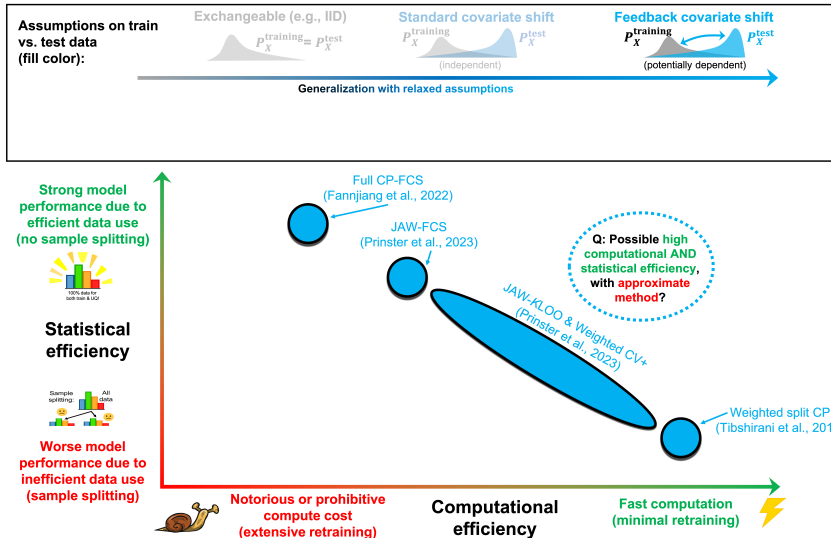
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# Related Work: Feedback Covariate Shift (FCS)

Related Work: High-Level Overview

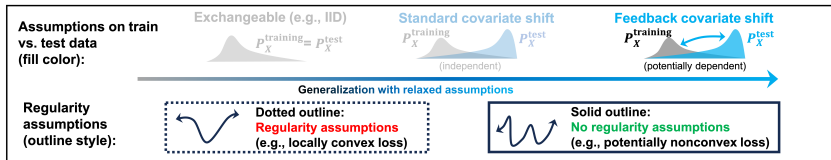
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# Related Work: Feedback Covariate Shift (FCS)

Related Work: High-Level Overview

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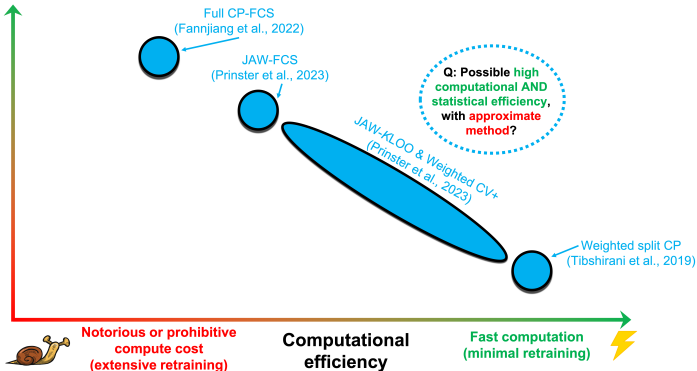
Strong model performance due to efficient data use (no sample splitting)



Statistical efficiency



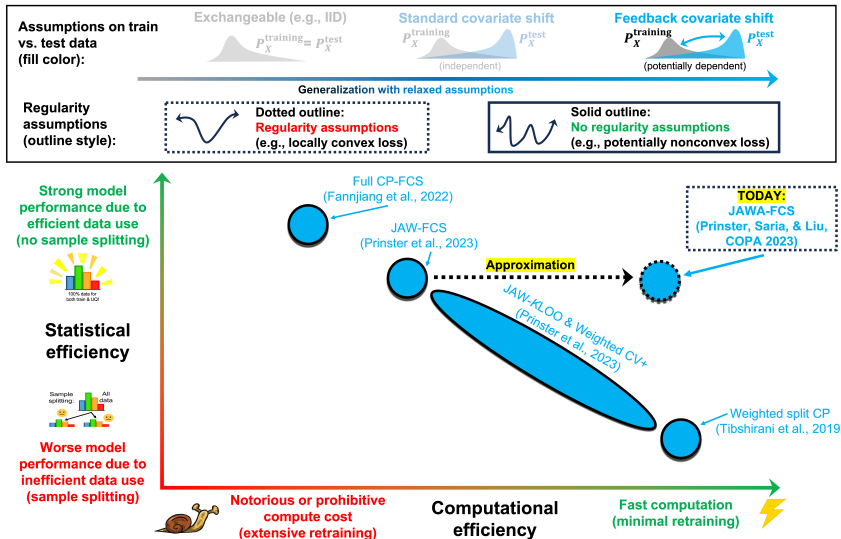
Worse model performance due to inefficient data use (sample splitting)



## Proposed Work: Approximation of JAW-FCS

## Related Work: High-Level Overview

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# Background: Jackknife+ Predictive Interval

Jackknife+ predictive interval (Barber, Candes, Ramdas, & Tibshirani, 2021):

$$\hat{C}_{n,\alpha}^{\text{Jackknife}+}(x) = \left[ Q_{\alpha} \left( \sum_{j=1}^n \frac{1}{n+1} \delta_{\hat{\mu}_{-j}(x) - |Y_j - \hat{\mu}_{-j}(X_j)|} + \frac{1}{n+1} \delta_{-\infty} \right), \right. \\ \left. Q_{1-\alpha} \left( \sum_{j=1}^n \frac{1}{n+1} \delta_{\hat{\mu}_{-j}(x) + |Y_j - \hat{\mu}_{-j}(X_j)|} + \frac{1}{n+1} \delta_{\infty} \right) \right]$$

Some notation:

- $\delta_v :=$  point mass at value  $v$
  - $\hat{\mu}_{-j} :=$  Leave-one-out (LOO) retrained model
- ⇒ Requires training  $n$  distinct predictors

# Background: JAckknife+ Weighted for FCS

(Fitted) likelihood ratio weights:

$$w(x; D) = \frac{dP_{X;D}^{\text{test}}(x)}{dP_X^{\text{train}}(x)}$$

e.g.,  
 $P_{X;D}^{\text{test}}(x) \propto \exp(\lambda \cdot \hat{\mu}(x))$

Normalized weights:

$$\tilde{w}_{n+1,j}(x) = \frac{\overbrace{w(x; Z_{-j})w(X_j; Z_{-j})}^{\text{weights for LOO pt } j \text{ and test pt } n+1}}{\underbrace{\sum_{j'=1}^n [w(x; Z_{-j'})w(X_{j'}; Z_{-j'})] + w(x; Z_{1:n})^2}_{\text{normalization constant}}}$$

**J**Ackknife+ **W**eighted for **F**eedback **C**ovariate **S**hift or “**JAW-FCS**”  
 (Prinster, Liu, & Saria, 2023):

$$\hat{C}_{n,\alpha}^{\text{JAW-FCS}}(x) = \left[ Q_\alpha \left( \sum_{j=1}^n \tilde{w}_{n+1,j}(x) \delta_{\hat{\mu}_{-j}(x) - |Y_j - \hat{\mu}_{-j}(X_j)|} + \tilde{w}_{(n+1)^2}(x) \delta_{-\infty} \right), \right. \\ \left. Q_{1-\alpha} \left( \sum_{j=1}^n \tilde{w}_{n+1,j}(x) \delta_{\hat{\mu}_{-j}(x) + |Y_j - \hat{\mu}_{-j}(X_j)|} + \tilde{w}_{(n+1)^2}(x) \delta_{\infty} \right) \right]$$

Note: Often  $w(\cdot; Z_{-j})$  and  $\hat{\mu}_{-j}$  require the same LOO parameter est.  $\hat{\theta}_{-j}$

# Background: Influence Functions

**Influence functions** (Cook, 1977; Giordano, Jordan, & Broderick, 2019) approximate model parameter changes due to removing (or reweighting) a datapoint via a  $K$ -th order Taylor series.

$$\hat{\theta}_{-i}^{\text{IF-}K} := \hat{\theta} + \sum_{k=1}^K \frac{1}{k!} D_{-i}^k \hat{\theta}$$

$D_{-i}^k \hat{\theta} := k$ th order derivative of parameters  $\hat{\theta}$  w.r.t. removing point  $i$

**Main computational cost: Computing inverse Hessian**

**Prior works using IFs with jackknife+:**

- Alaa and Van Der Schaar (2020) used higher order IFs to approximate the Jackknife+, but assume i.i.d. data
- Prinster, Liu, and Saria (2022) used higher orders to approximate the JACKknife+ Weighted for *Standard* Covariate Shift (JAW-SCS), but with different weights than in FCS



# Proposed Method: JAWA-FCS

**JAWA-FCS: J**ackknife **W**eighted **A**pproximation for **F**eedback **C**ovariate Shift ( $K$ -th order Influence Function)

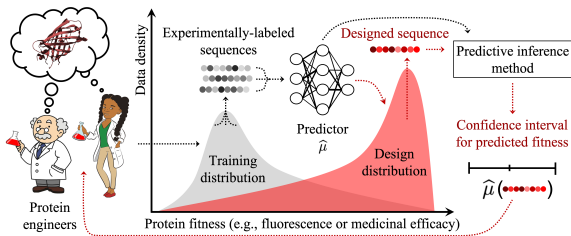
$$\begin{aligned} \hat{C}_{n,\alpha}^{\text{JAWA-FCS}}(x) &= \left[ Q_\alpha \left( \sum_{j=1}^n \tilde{w}_{n+1,j}^{\text{IF-K}}(x) \delta_{\hat{\mu}_{-j}^{\text{IF-K}}(x) - |Y_j - \hat{\mu}_{-j}^{\text{IF-K}}(X_j)|} + \tilde{w}_{(n+1)^2}^{\text{IF-K}}(x) \delta_{-\infty} \right), \right. \\ &\quad \left. Q_{1-\alpha} \left( \sum_{j=1}^n \tilde{w}_{n+1,j}^{\text{IF-K}}(x) \delta_{\hat{\mu}_{-j}^{\text{IF-K}}(x) + |Y_j - \hat{\mu}_{-j}^{\text{IF-K}}(X_j)|} + \tilde{w}_{(n+1)^2}^{\text{IF-K}}(x) \delta_{\infty} \right) \right] \end{aligned}$$

**Main idea:** Approximating both the weights  $w(\cdot; Z_{-j})$  and LOO predictions  $\hat{\mu}_{-j}$  using influence functions (IFs)

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# Experiments: Fluorescent Protein Design Task

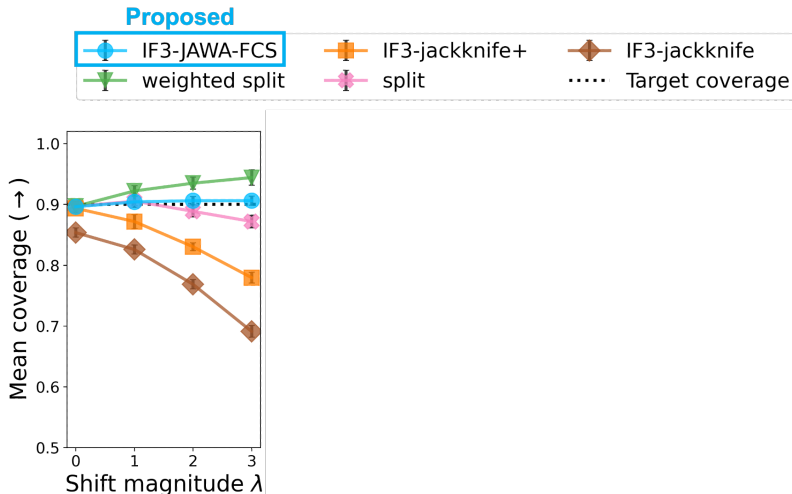


## Experimental details:

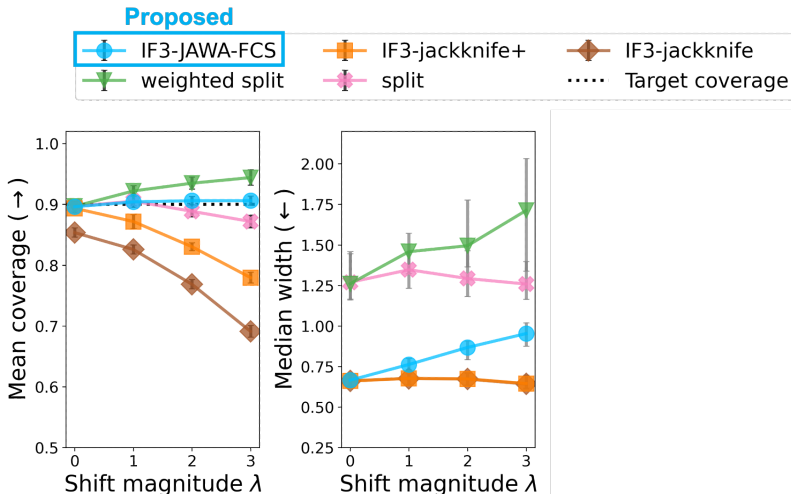
- $\hat{\mu}$ : Small (25 hidden unit) neural network regressor with tanh activation function
- 0.5 L2 regularization parameter
- $n = 192$  training samples
- $K = 3$ rd order influence function approximation
- $\alpha = 0.1$
- 20 experimental replicates

Runtime results: **JAWA-FCS: <3 minutes**     **JAW-FCS: 1 hour 24 minutes**

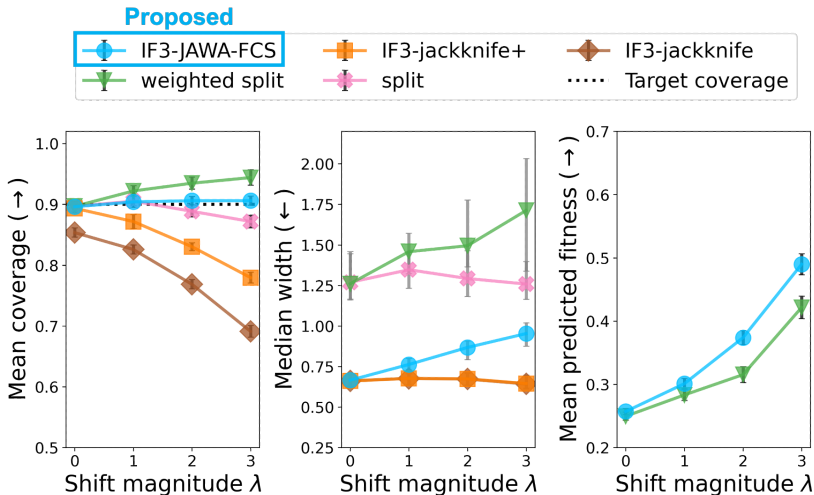
# Flourescent Protein Design Results



# Flourescent Protein Design Results



# Flourescent Protein Design Results



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## Limitations and future directions:

- Experiments only with small neural net  $\hat{\mu} \Rightarrow$  See if results scale to larger  $\hat{\mu}$
- Empirical contribution only  $\Rightarrow$  See how IF approximation error would impact guarantees.
- E.g., Giordano et al. (2019) give consistency conditions for LOO IF approximation (but do not consider guarantees for prediction estimates or coverage):
  - $\hat{\theta}$  is local minimum of objective function
  - Existence and boundedness of higher-order derivatives
  - Objective is strongly convex in neighborhood of  $\hat{\theta}$



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# Acknowledgements

Thank you!!

